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Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	4677	703/?clds.	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:05
L2	4594	(hybrid with (model\$3 or simulat\$5))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:06
L3	1402	(kinematic\$2 with (model\$3 or simulat\$5))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:07
L4	23	I2 and I3	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:20
L5	567	(I2 or I3) and (select\$3 with variabl\$2)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:21
L6	13	(I2 or I3) with (select\$3 with variabl\$2)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:31
L7	52868	(variabl\$2 with mechanism)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:31
L8	91	I2 and I7	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:32
L10	3	I3 and I8	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:34
L11	498	I2 and ((calculat\$3 or perform\$3) with variabl\$2)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:39
L12	6	I3 and I11	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:35
L13	29	I2 and (((calculat\$3 or perform\$3) and predefin\$3) with variabl\$2)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:48
L14	255	I3 and ((operat\$3 or behavior or three\$dimension\$3) with mechanism)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:49
L15	382	I2 and ((operat\$3 or behavior or three\$dimension\$3) with mechanism)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:49
L16	10	I14 and I15	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:51
L17	29279	((dynamic\$2 or hybrid) with (model\$3 or simulat\$4))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:53
L18	486	I3 and I17	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:55
L19	1	I13 and I18	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:53
L20	52	I18 and ((continuous or differential) and state with transition)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:56

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L21	52	I18 and ((continuous or differential) and (state with transition))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:56
L22	41	I21 and (rotation or displac\$5)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 14:57
L23	47	I21 and (rotat\$3 or displac\$5)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 15:16
L27	11	((select\$3 or perform\$3) with variabl\$2) with (hybrid with (model\$2 or simulat\$5))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 15:23
L28	3936	(hybrid with (language or description))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 15:24
L29	6	I3 and I28	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 15:55
L30	152	I1 and I2	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 15:55
L31	84	I1 and I3	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 15:55
L32	5	I30 and I31	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/30 15:56

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Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	1	("5831853").PN.	USPAT; USOCR	OR	OFF	2006/12/27 12:26
S2	23	("4991176" "5038307" "5056014" "5125098" "5161115" "5163016" "5287194" "5301100" "5325528" "5363175" "5485600" "5542070").PN. OR ("5831853").URPN.	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:10
S3	4675	703/?ccls.	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:11
S4	32	S3 and (hybrid adj (model\$3 or simulat\$5))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:25
S5	9	S4 and (continu\$3 and transit\$4)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:12
S6	450	(kinematic\$2 adj (model\$3 or simulat\$5))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:25
S7	538	(hybrid adj (model\$3 or simulat\$5))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:25
S8	4	S6 and S7	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:27
S9	303	(state with transition) and (hybrid with model)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:27
S10	90	dynamic with simulation and kinematic with simulation	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:29
S11	14	S10 and hybrid	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:42
S12	5	hybrid with kinematic\$2 with dynamic\$2	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:46
S13	149	mechanism with simulat\$4 and hybrid with (model\$3 or simulat\$5)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:47
S14	106	S13 and (variabl\$2 and element\$2)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:48
S15	5	S13 and (class with hybrid)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:50
S16	203	kinematic\$2 with simulation	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:50
S17	401	kinematic\$2 with simulat\$4	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:51
S18	1399	kinematic\$2 with (model\$3 or simulat\$4)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:51
S19	4589	hybrid\$2 with (model\$3 or simulat\$4)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:57

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S20	23	S18 and S19	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:51
S21	91	hybrid\$2 with (model\$3 or simulat\$4) with language	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 15:57
S22	4	S18 and S21	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:03
S23	507	S19 and (generat\$3 with table)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:03
S24	75	S23 and (state with transition)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:04
S25	58	S24 and (continuous or differential or ode)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:05
S26	18	S24 and ((continuous or differential or ode) with equation)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:09
S27	110	(hybrid with (simulat\$4 or model\$3)) and (behavior with mechanism)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:12
S28	31	(hybrid with (simulat\$4 or model\$3)) and (behavior with mechanism) and state with transition	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:13
S29	17	S28 and (continuous or differential) with (equation or system)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:20
S30	493	((continuous or differential) with (equation or system)) and (hybrid with model)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:20
S31	73	((continuous or differential) with (equation or system)) and (hybrid with model) and (generat\$3 with table)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:21
S32	1	((continuous or differential) with (equation or system)) and (hybrid with model) same(generat\$3 with table)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:24
S33	98	variable with (hybrid with (model\$3 or simulat\$4))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:26
S34	31	variable with (hybrid with (model\$3 or simulat\$4)) and (generat\$3 with (table or diagram))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:27
S35	33	variable with (hybrid with (model\$3 or simulat\$4)) and (generat\$3 with (table or diagram or block))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 16:28
S36	15	variable with (hybrid with (model\$3 or simulat\$4)) and (generat\$3 with (table or diagram or block))same class	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 17:58
S37	538	(hybrid adj (model\$3 or simulat\$4))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 17:59
S38	274	S37 and (continuous or differential or ode)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 18:03

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S39	544	(kinematic\$2 adj2 (model\$3 or simulat\$4))	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 18:00
S40	21	S39 and ((operation or behavior or three\$dimension\$2) near2 mechanism)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 18:03
S41	2	S38 and S40	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 18:01
S42	289	S39 and (continuous or differential or ode)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 18:03
S43	16	S42 and ((operation or behavior or three\$dimension\$2) near2 mechanism)	US-PGPUB; USPAT; USOCR	OR	ON	2006/12/27 18:03
S44	2	"20030115031"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/12/28 08:13